



CMRE's input to ONR Seabed Characterization Experiment 2016

Seabed characterization using hydrophone equipped gliders and active sources

Yong-Min Jiang and Peter L. Nielsen

NATO – STO – CMRE

Viale San Bartolomeo 400, 19126, La Spezia, Italy





REP series:

- **REP11**: Ocean environmental variation on acoustic signal fluctuations
 - Acoustic signals were collected by a 32 elements VLA
- **REP12**(NOMR12): Sonar performance validation (signal excess)
 - Acoustic signals were collected by a 32 elements VLA, a bottom moored tetrahedral array and a hydrophone equipped glider
- **REP13**: Acoustic evaluation of a heterogeneous data collection asset-network
 - Acoustic signals were collected by a 32 elements VLA and hydrophone equipped glider (with reactive behavior)
- REP14: a) Bottom characterization using man-made and naturally occurring ambient noise, and b) In-situ acoustic received level measurements with glider based reactive behavior
 - Acoustic signals were collected by two 32 elements VLAs, one 8-element VLA, one 8-element compact volumetric array, two hydrophone equipped gliders (with reactive behavior)
 - In an inhomogeneous area (bottom layer structure)

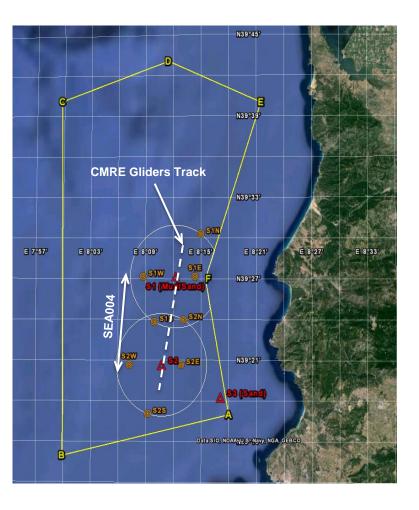
GLASS: 2012 and 2013, Peter Nielsen

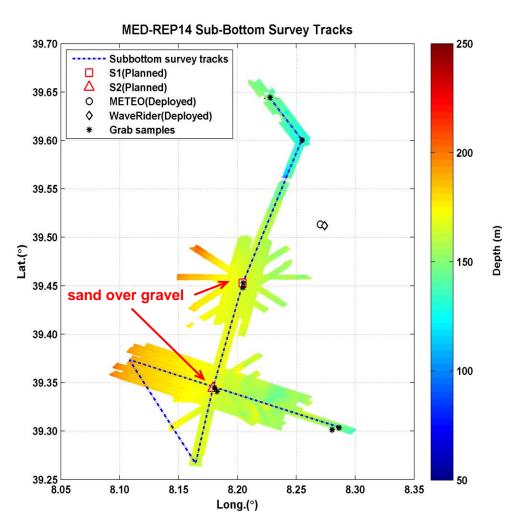


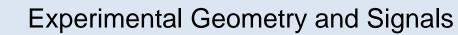
Experimental Site



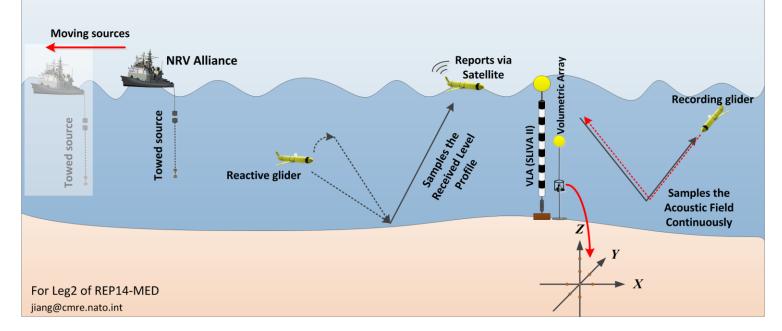
12 June to 21 June, 2014 (including transit and port call)







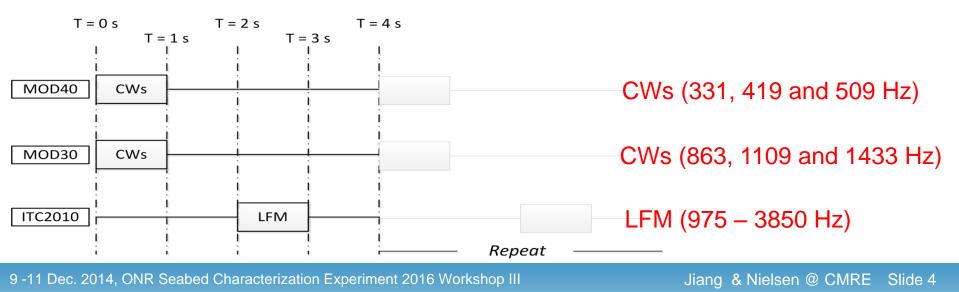




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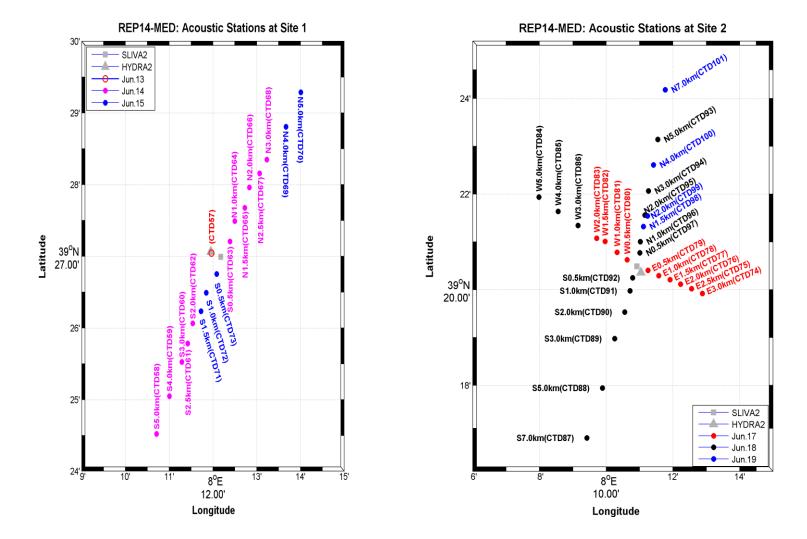
OTAN

REP14-MED:



Acoustic stations with active sources - Heterogeneous bottom structure





Total 44 acoustic stations and 45 CTDs

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REP14-MED:

NRV Alliance as sound sources

REP14-MED Ship Radiated Noise Measurement Tracks



250

0 WaveRider SLIVA2@Site 1 39.65 HYDRA2@Site 1 Δ SLIVA2@Site 2 Δ HYDRA2@Site 2 39.60 200 39.55 Total 12 high speed (12 knots) tracks 0 Depth (m) 39.50 and 12 low speed Lat.(∘) (6 knots) tracks 39.45 39.40 100 39.35 39.30 39.25 8.05 50 8.10 8.15 8.20 8.25 8.30 8.35 Long.(°)

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REP14-MED:

39.70

0

METEO buoy



Bottom moored arrays



CVA (HYDRAII) :

3D cross array 8 elements Spacing: 0.16 m



VLA (SLIVAII) : Reference array 32 elements 46.5 m long Spacing: 1.5 m



9 -11 Dec. 2014, ONR Seabed Characterization Experiment 2016 Workshop III

REP14-MED: Hydrophone equipped gliders (reactive)



Hydrophones



CMRE (with reactive behavior)

9 -11 Dec. 2014, ONR Seabed Characterization Experiment 2016 Workshop III

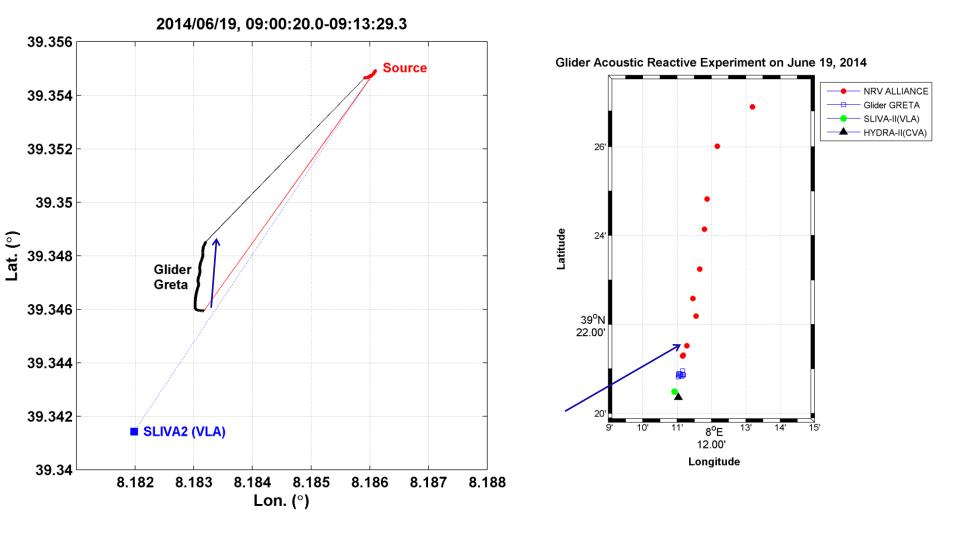
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Jiang & Nielsen @ CMRE Slide 8

REP14-MED: Hydrophone equipped gliders (reactive)





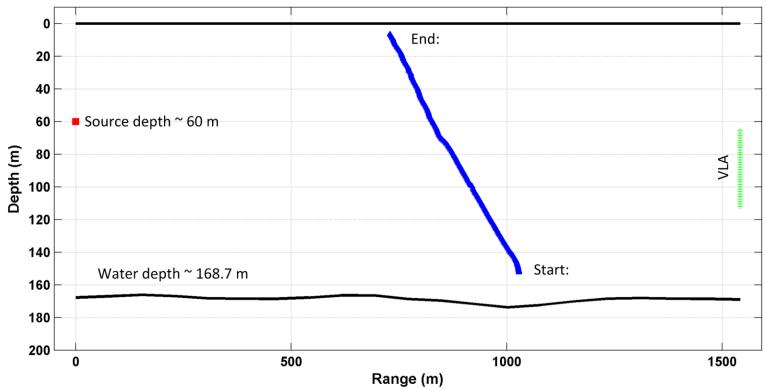
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The experimental geometry:



REP14-MED, 19 June 2014, 09:00:20 - 09:13:30

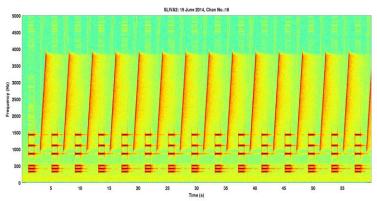
Inversion: VLA and hydrophone equipped glider comparison



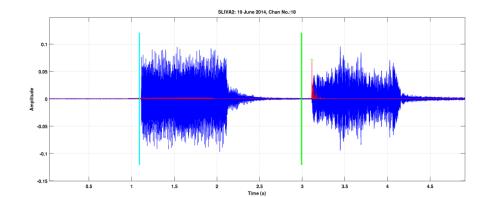
VLA data:

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Glider data:



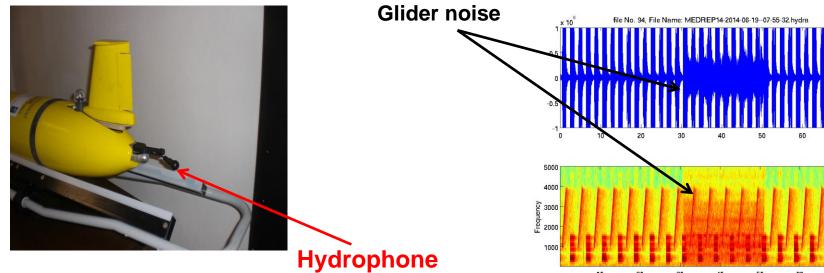
10

20

30

40

Time



9 -11 Dec. 2014, ONR Seabed Characterization Experiment 2016 Workshop III

50

60

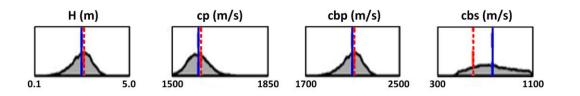
70





□ Preliminary results (sensitive parameters only)

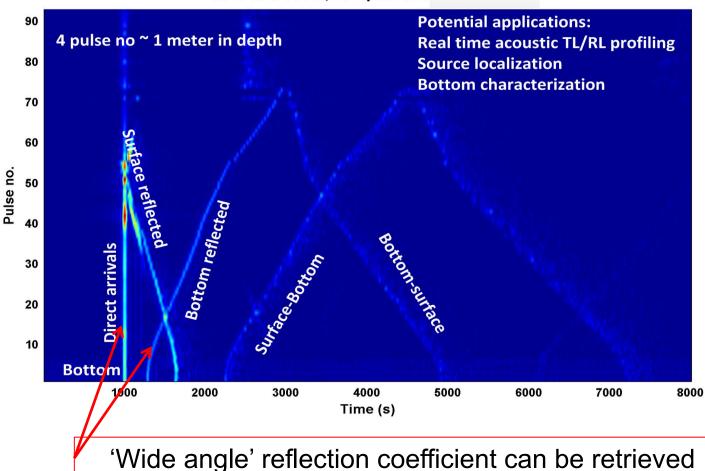
- There is sensitivity in the shear wave speed of the half space
- p-wave speed of the half-space seems to be higher than expected



Grey area: 1-D marginal distribution from VLA data, Blue line: maximum a posterior Red dotted line: optimization results from glider data





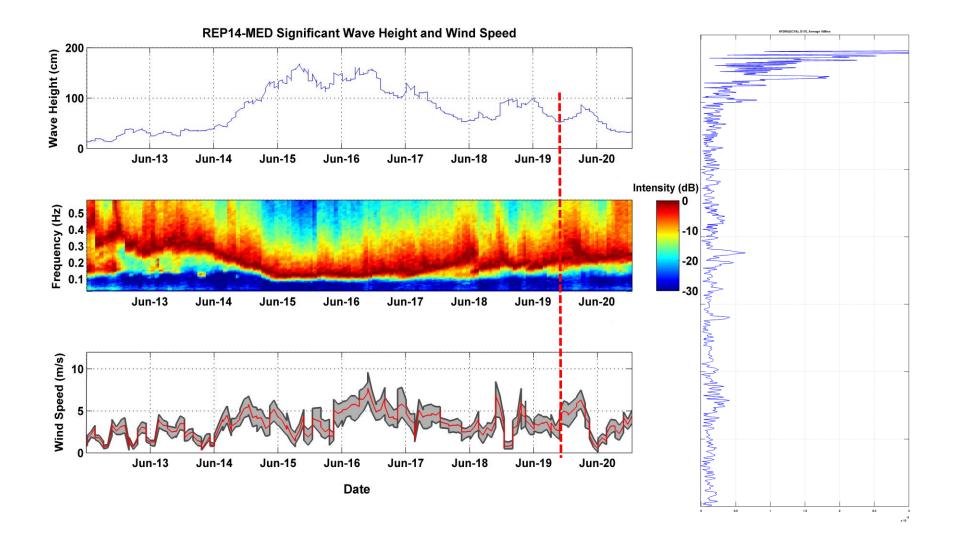


MED-REP14 ET, 23 April 2014



CVA as passive fathometer









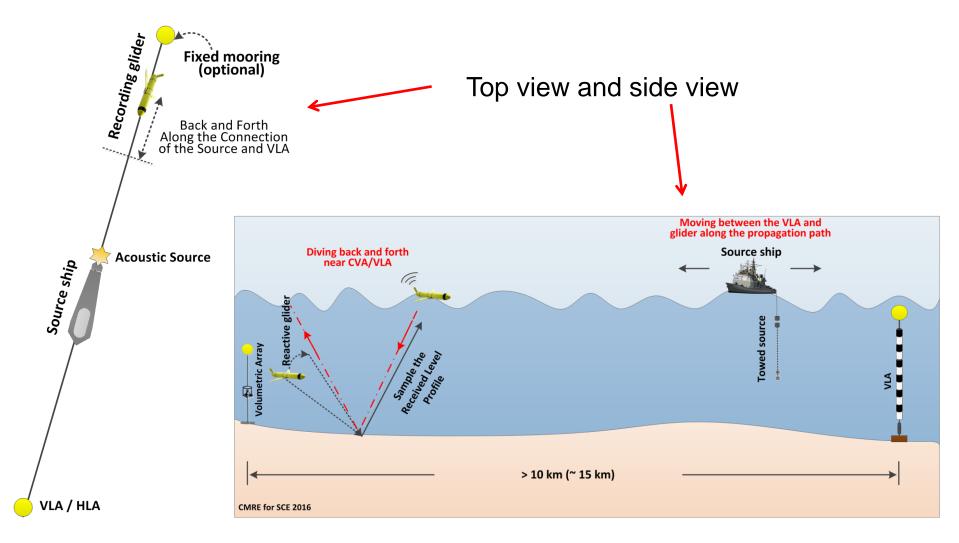
Glider 'network' Bottom characterization: arrays on glider, with active sources/ambient noise **Tested in REP14-MED** CVS - 'Vector' sensor concept Complementary to GI using naturally occurring noise approach Use ship noise / active sources Smaller in size 'super directionality' **Glider network** Next year (2015) (8-element VLA) Glider equipped with Compact Volumetric Array Glider equipped with **One** hydrophone (8 sensors ~ 'vector' sensor) **CVA and VLA**

9 -11 Dec. 2014, ONR Seabed Characterization Experiment 2016 Workshop III





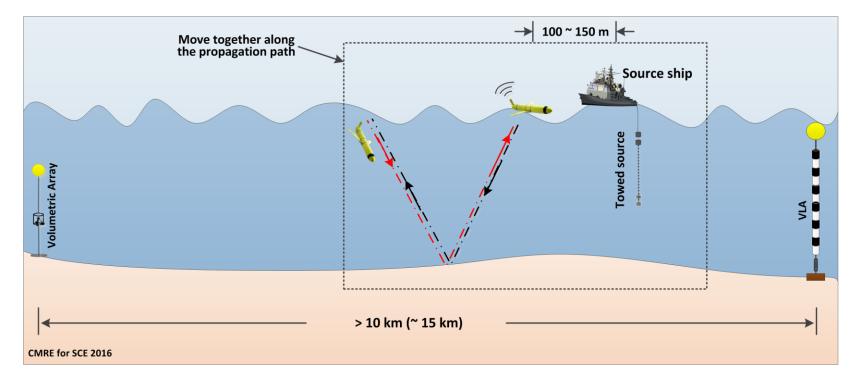
• Longer range: cross check the inversion results at both ends







- Wide angle reflection coefficient measurements with mobile platforms
 - What do we do with local information?
 - Does the local information add value to long range propagation?







- CMRE has stuff...however it's hard to ship them over (maintain and deploy)
 - For example: 32 elements , 46.5 m long VLA with radio buoy
- But, we have:
 - Bottom moored HYDRA systems (suitable for deep water deployments, at least two people)
 - 4 elements tetrahedral structure
 - 8 elements compact volumetric array (array spacing variable)
 - 8 elements vertical line array (Peter Nielsen, array spacing variable)
 - Hydrophone equipped underwater glider(at least two people)
 - With reactive behavior
 - Can sample the acoustic field and CTD at the same time
 - Arrays on gliders (8-element compact volumetric and vertical arrays) to be tested in 2015